

# Batched Multi Triangulations

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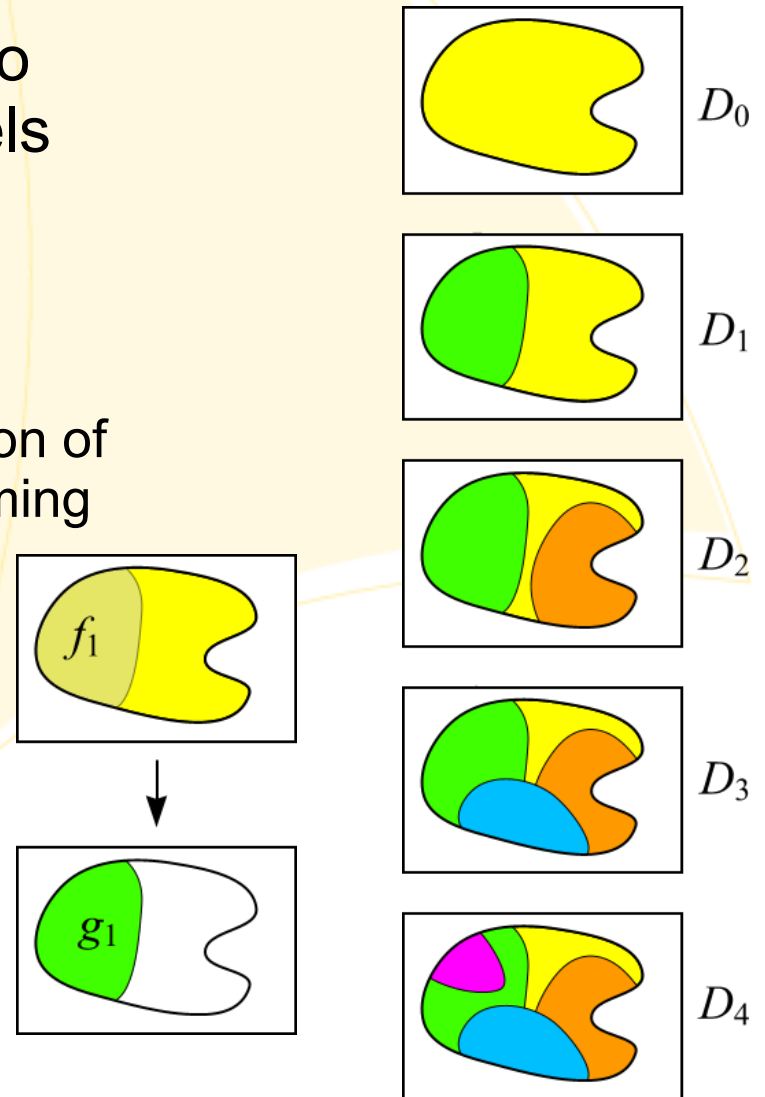
*Accurate adaptive efficient rendering  
of very large static meshes*

- Isosurfaces, scanned objects etc
- Hundreds of papers.
- Recent trends in multires surface representation (some)
  - To harness the power of graphics hw
  - Out of core management
  - Low CPU usage approaches

- MT is a well known framework to describe a multiresolution models
- Consider a sequence of local modifications over a given description  $D$ 
  - Each modification replaces a portion of the domain with a different conforming portion (simplified)
  - $f_i$  floor
  - $g_i$  the new fragment

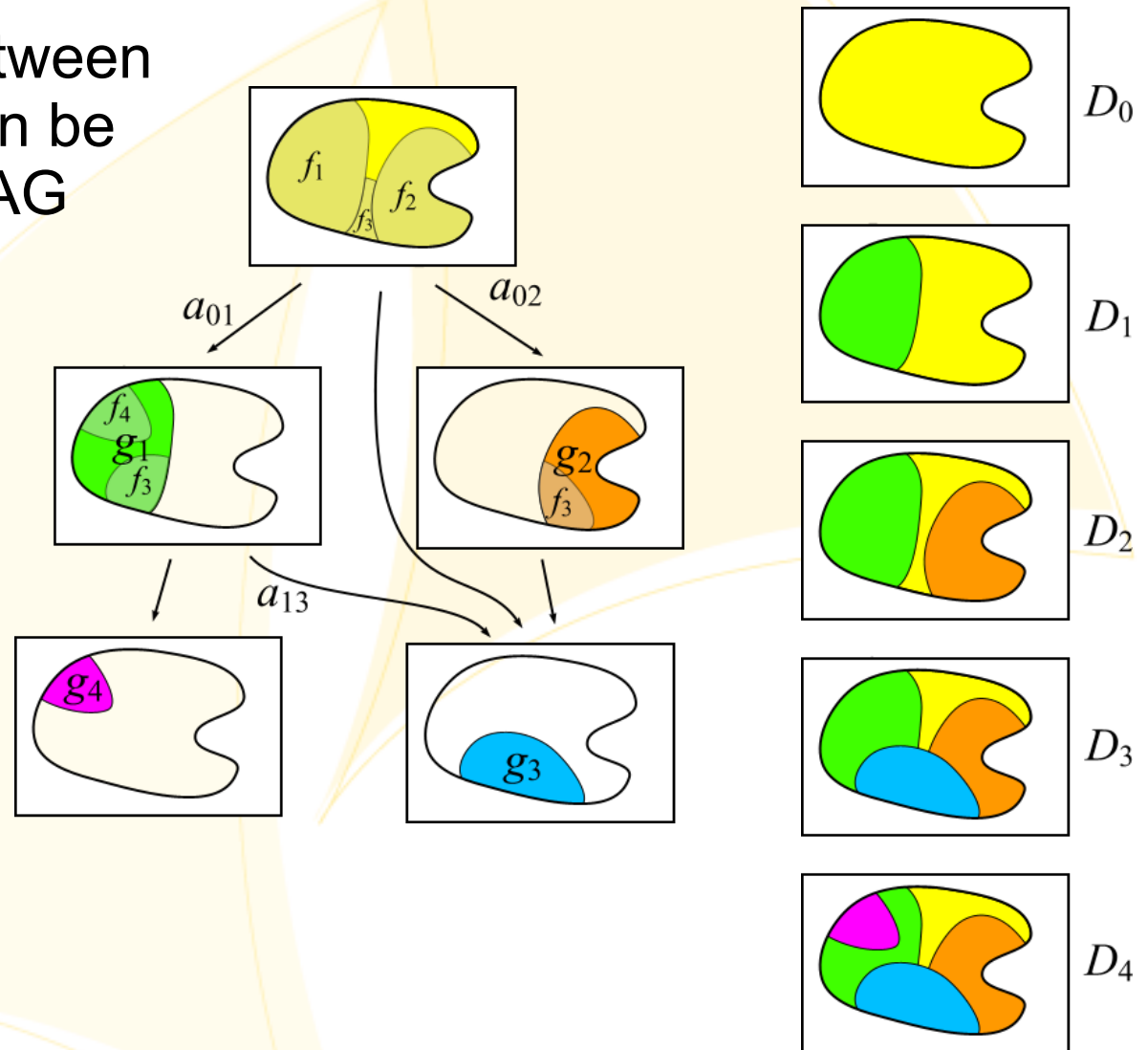
$$D' = D \setminus f \cup g$$

$$D_{i+1} = D_i \oplus g_{i+1}$$



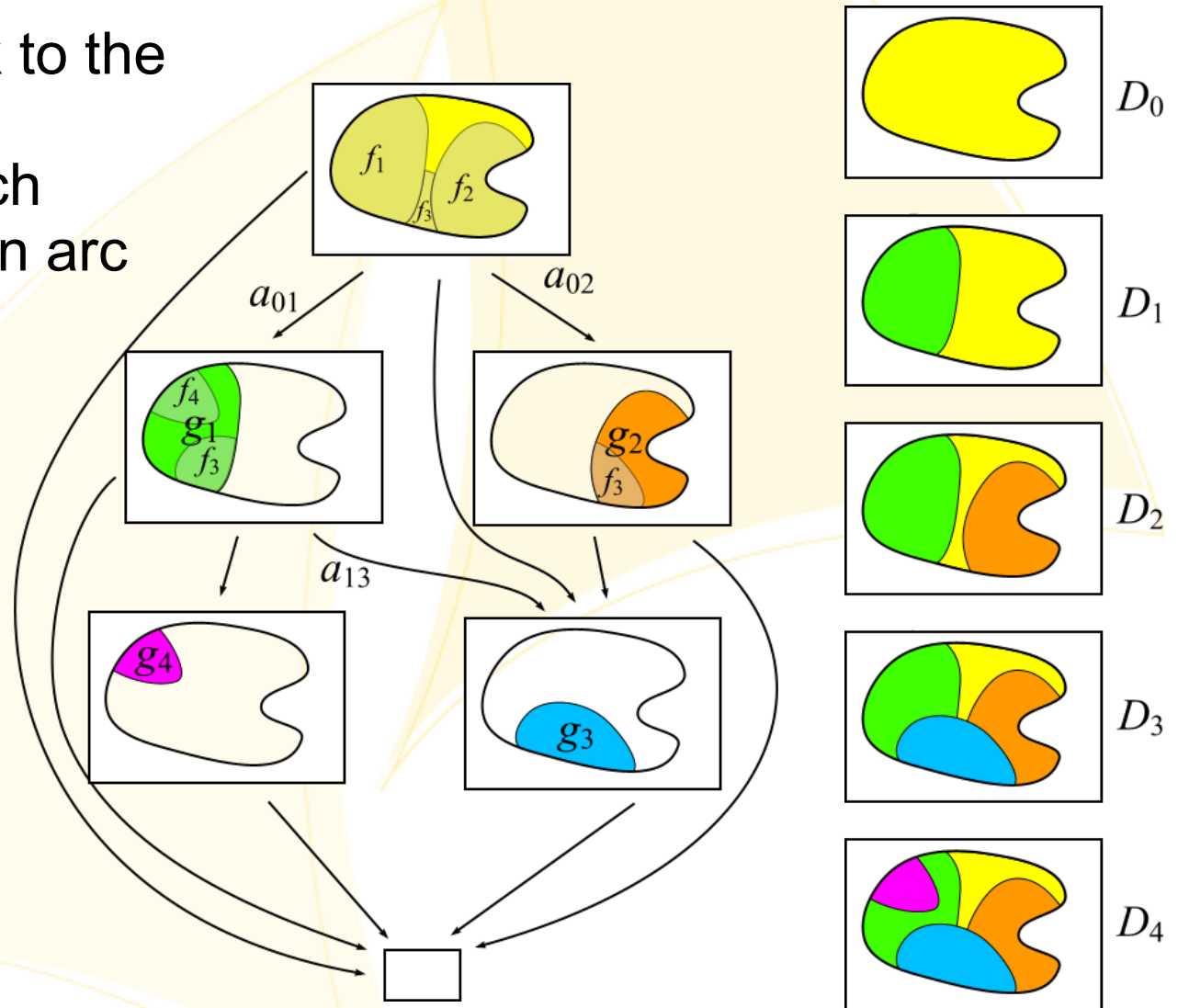
# Multi Triangulations

- Dependence between modifications can be arranged in a DAG



# Multi Triangulations

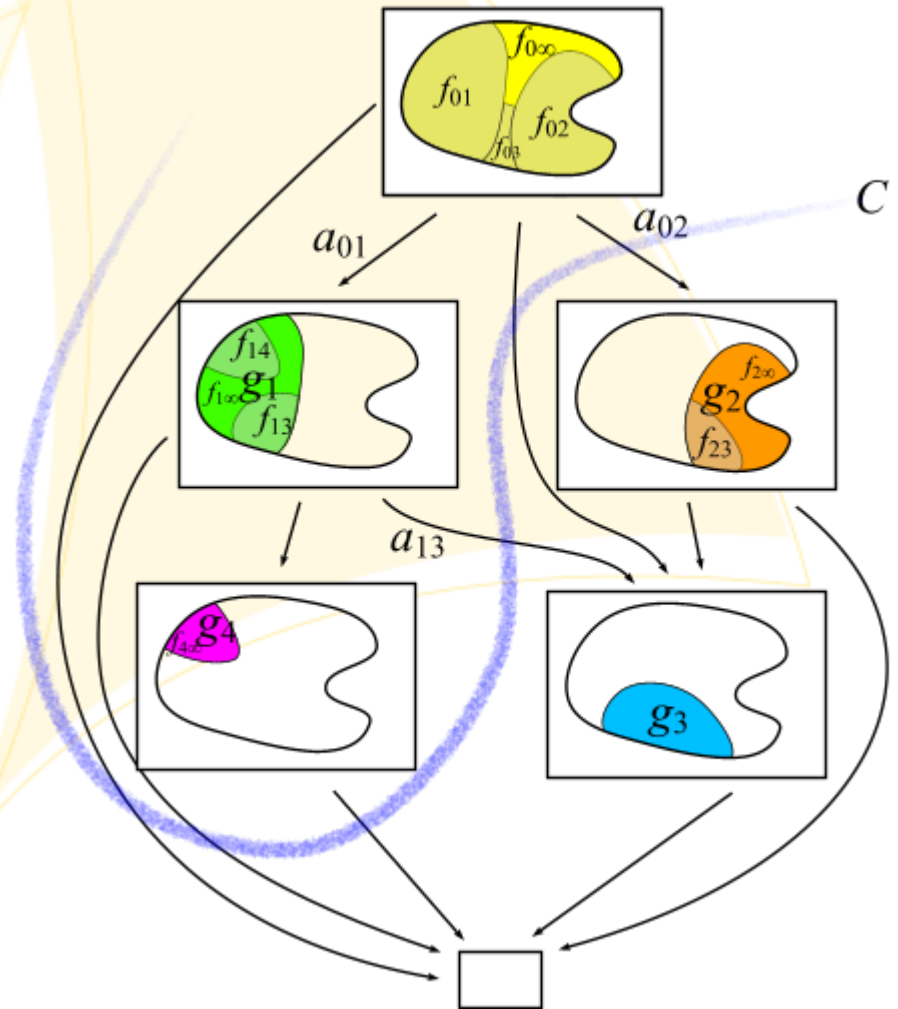
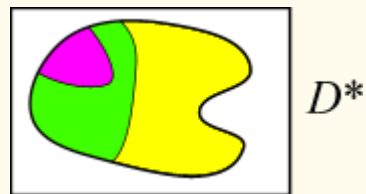
- Adding a sink to the DAG we can associate each fragment to an arc



# MT Cuts

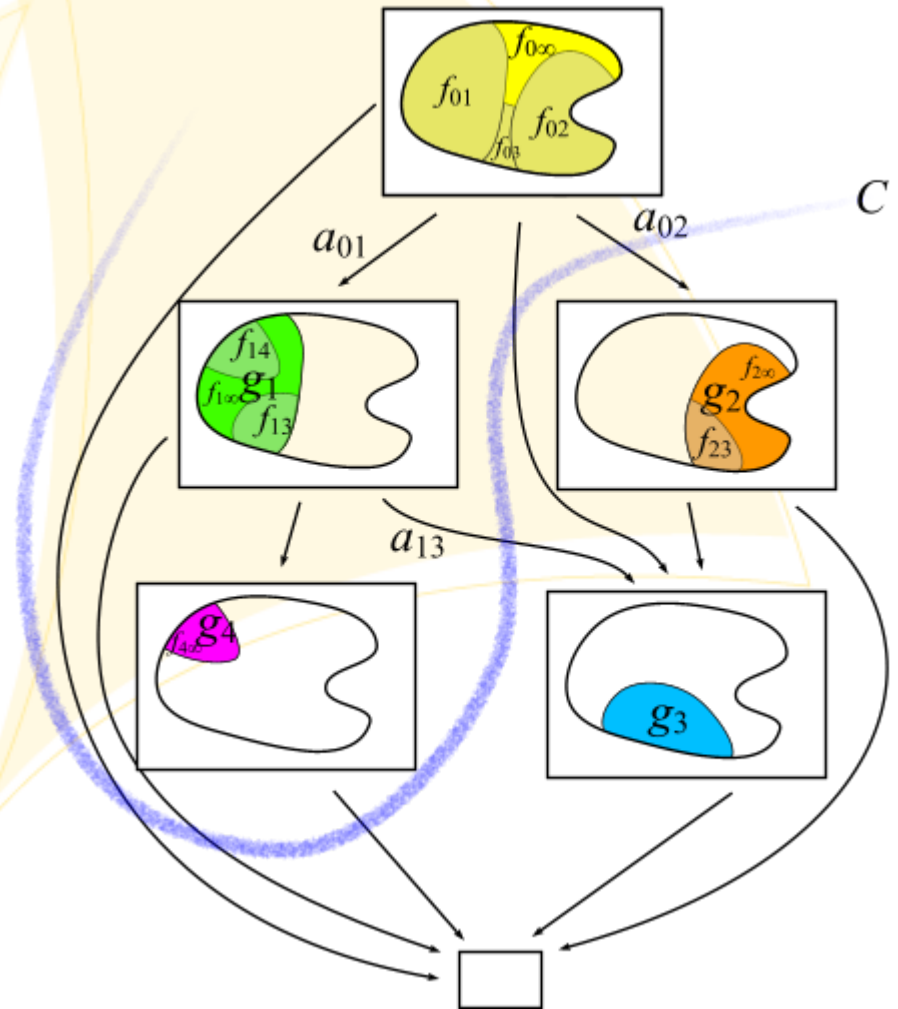
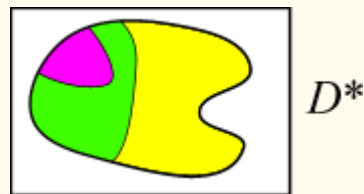
➤ A cut on the DAG defines a new representation

➤



$$D^* = D_0 \oplus g_1 \oplus g_2 \oplus g_4$$

- A cut on the DAG defines a new representation
- Collect all the fragment floors of cut arcs and you get a new conforming mesh
  - just load and render
  - low cpu workload
  - fit very well in extended memory hierarchies

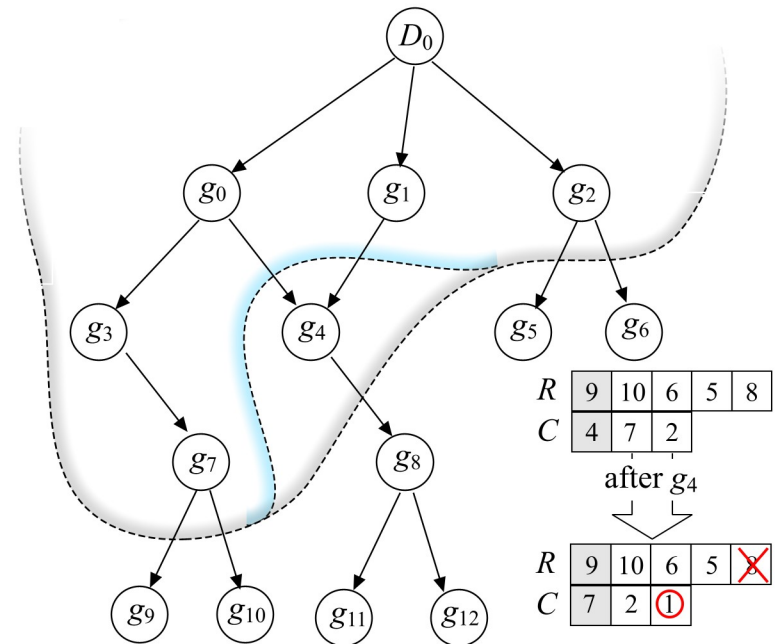


$$D^* = D_0 \oplus g_1 \oplus g_2 \oplus g_4 = f_{0\infty} \cup f_{02} \cup f_{03} \cup f_{13} \cup f_{1\infty} \cup f_{4\infty}$$

- Fragment are patches of triangles
  - Optimized (tristripped) and stored compressed on disk
  - Obtained with an high quality simplification alg.
  - DAG  $\ll$  original mesh (patches composed by 8k tri)
- At run time two threads: Render and PatchServer
  - **Render**
    - Update the cut (moving in and out MT nodes)
    - Choose patches to be prefetched
    - Render the selected fragments
  - **PatchServer**
    - Load and uncompress requested patches from disk into memory
- Culling
  - Standard frustum and hw based occlusion techniques defined for generic hierarchies can be easily adapted to DAGs



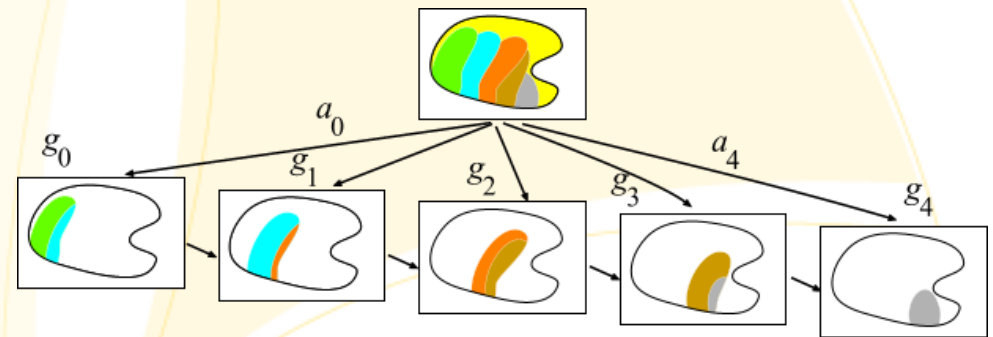
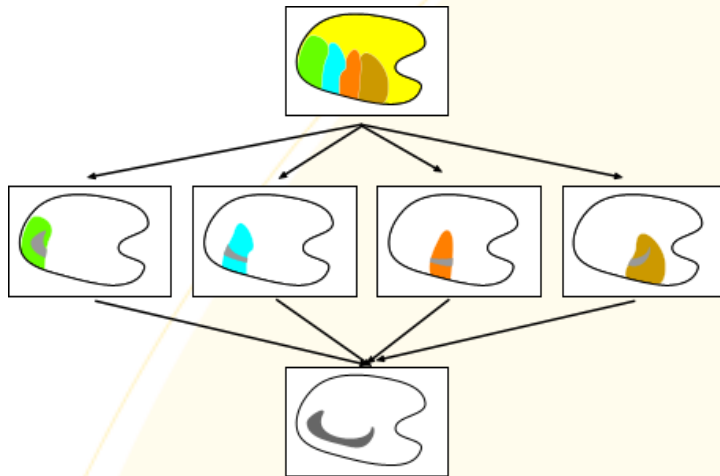
- To update the cut we use two priority queues R & C for refinement and coarsening of MT nodes
  - R top is **max** screen space error
  - C top is **min** screen space error
- Cost function for each node
  - According to its size and if it is loaded
- Refine until budget is full
- Coarsen otherwise
- Take care of node feasibility



# Not well conditioned Dag

## ➤ Possible DAG problems:

- The topology of dependencies lowers the adaptivity of the multiresolution structure
- Cascading dependencies are BAD

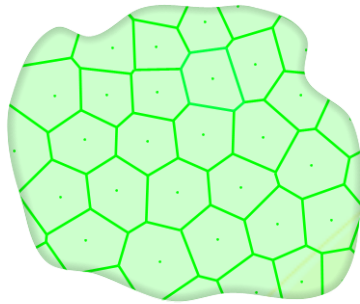


Goal: Building a nice sequence of fragments

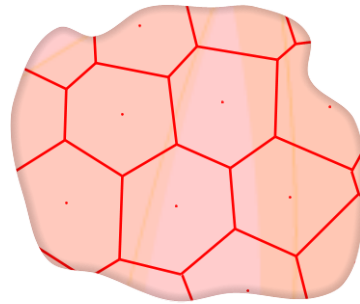
- Consider a partition  $\Psi$  of the space into disjoint regions  $\{\psi_j\}$ 
  - Partitions can be applied to triangulations
- Given two partitions  $\Psi, \Phi$  we define the *crossing* of the partitions as

$$\Psi \otimes \Phi = \bigcup_{i=0 \dots |\Psi|, j=0 \dots |\Phi|} \{\psi_i \cap \phi_j\}$$

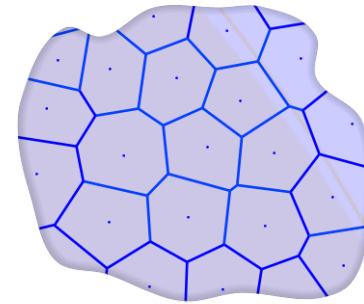
# Crossing Partitions



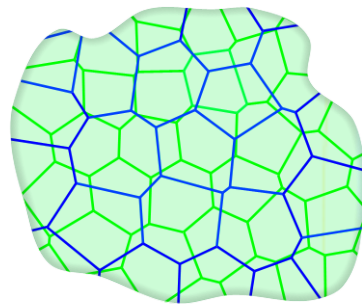
$V_0$



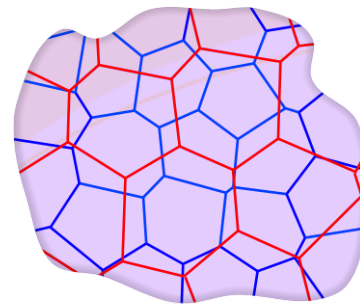
$V_1$



$V_2$



$V_0 \otimes V_1$

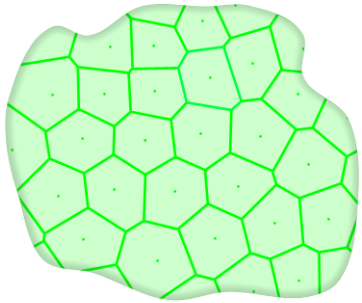


$V_1 \otimes V_2$

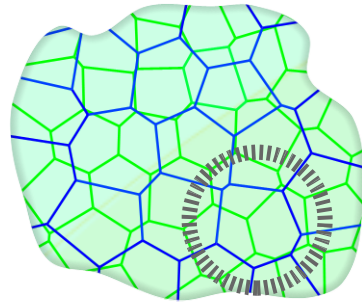
## MT and sequence of partitions

- At step  $i$  we substitute independently all the regions of a partition  $V_i$  with a simpler representation.
- Iterating this process generates a set of fragments belonging to the various *crossing* of the partitions  $V_{i-1} \otimes V_i$  and  $V_i \otimes V_{i+1}$
- These pieces (the portions of floor fragments) are the building blocks that we will use to build new conforming triangulations

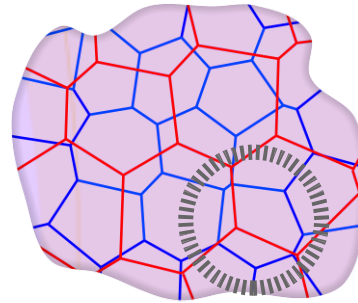
# Partitions in practice: Simplification



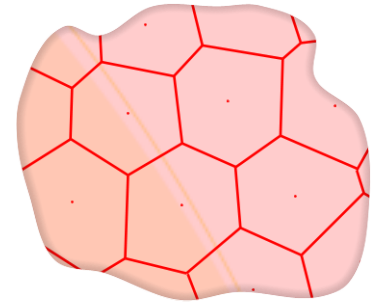
$V_{i-1}$



$V_{i-1} \otimes V_i$

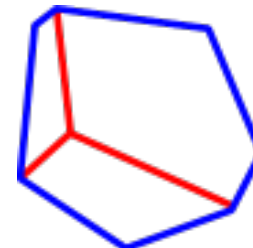


$V_i \otimes V_{i+1}$

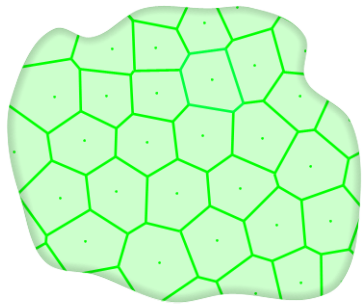


$V_{i+1}$

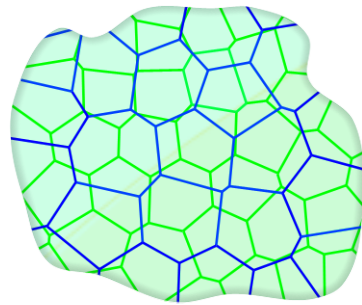
- Load the patches of  $V_{i-1} \otimes V_i$  that compose a region of  $V_i$
- Join and simplify preserving just the blue border
  - Simplification of patches is independent (out of core and parallel)
- Save this region partitioned according to  $V_i \otimes V_{i+1}$



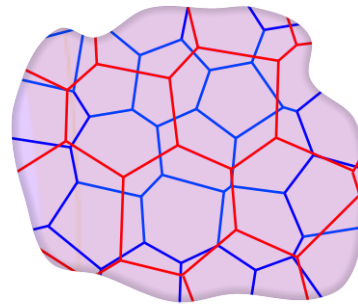
# MT in action



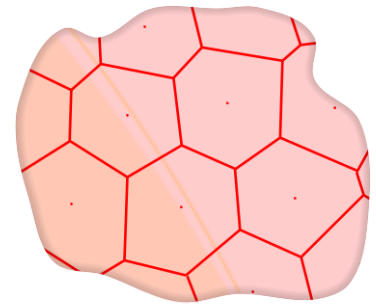
$V_0$



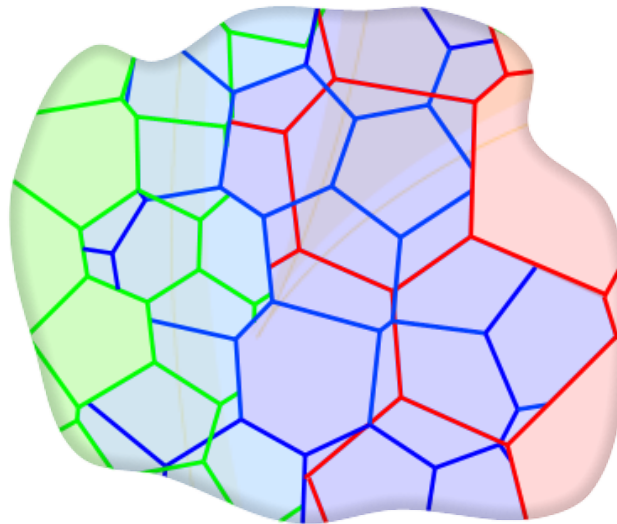
$V_0 \otimes V_1$



$V_1 \otimes V_2$



$V_2$

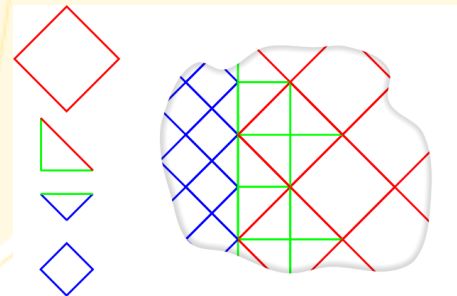
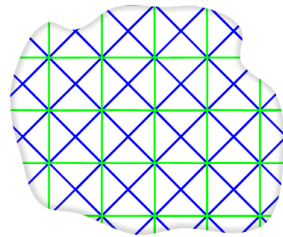
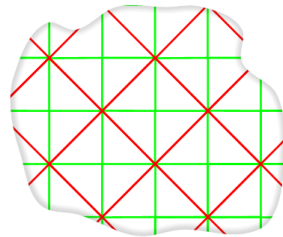
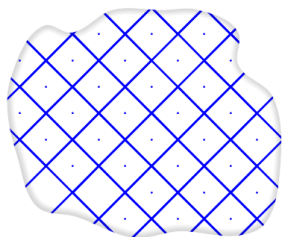
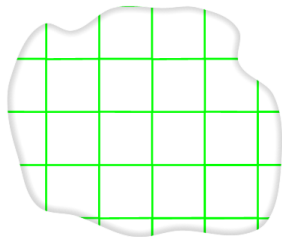
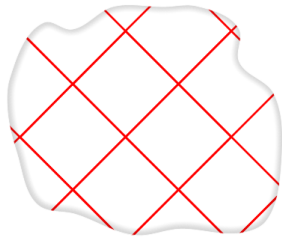


high resolution low

- We need a sequence of nice partitions
- Voronoi partitioning of space
  - Nice shape of the regions
  - Easy to attribute triangles to regions
  - generating seeds
- Regularly sampled seeds
  - Finer and finer grids
- Adaptive distribution of seed
  - Choose a patch radius  $r$
  - Stream the triangles adding a seed every time we encounter a triangle farther than  $r$  from all previous seeds
  - Apply Lloyd relaxation



- Encompasses existing partitioning schemas like right angle hierarchies and Tetrapuzzles/SlowGrowingSubdivisions



- Yet another multiresolution algorithm for rendering large static meshes.
  - General framework
  - Easy to implement
  - State of the art performance
    - >4Mtri/frame at >30 fps

